

UTILITY PATENT APPLICATION TRANSMITTAL

(Only for new nonprovisional applications under 37 CFR 1.53(b))

APPLICATION ELEMENTS

See MPEP chapter 600 concerning utility patent application contents.

Fee Transmittal Form
(Submit an original, and a duplicate for fee processing)

2. ☒ Specification Total Pages **31**

3. ☒ Drawings(s) (35 USC 113) Total Sheets **9**

4. ☒ Oath or Declaration Total Pages **1**

a. ☒ Newly executed (original or copy)

b. ☐ Unexecuted for information purposes

c. ☐ Copy from a prior application (37 CFR 1.63(d))
(for continuation/divisional with Box 17 completed)
(Note Box 5 below)

d. ☐ **DELETION OF INVENTOR(S)**
Signed Statement attached deleting inventor(s) named in
the prior application, see 37 CFR 1.63(d)(2) and 1.33(b).

5. ☐ Incorporation By Reference (useable if Box 4c is checked)
The entire disclosure of the prior application, from which a copy of the oath or
declaration is supplied under Box 4c, is considered as being part of the disclosure of
the accompanying application and is hereby incorporated by reference therein.

Attorney Docket No. 35.C13816

First Named Inventor or Application Identifier

SHIN MOSI, ET AL.

Express Mail Label No.

ADDRESS TO:

Assistant Commissioner for Patents
Box Patent Application
Washington, DC 20231

6. ☐ Microfiche Computer Program (Appendix)

7. Nucleotide and/or Amino Acid Sequence Submission
(if applicable, all necessary)

a. ☐ Computer Readable Copy

b. ☐ Paper Copy (identical to computer copy)

c. ☐ Statement verifying identity of above copies

ACCOMPANYING APPLICATION PARTS

8. ☒ Assignment Papers (cover sheet & documents)

9. ☐ 37 CFR 3.73(b) Statement (when there is an assignee) ☐ Power of Attorney

10. ☐ English Translation Document (if applicable)

11. ☐ Information Disclosure Statement (IDS)/PTO-1449 ☐ Copies of IDS Citations

12. ☐ Preliminary Amendment

13. ☒ Return Receipt Postcard (MPEP 503)
(Should be specifically itemized)

14. ☐ Small Entity Statement(s) ☐ Statement filed in prior application
Status still proper and desired

15. ☐ Certified Copy of Priority Document(s)
(if foreign priority is claimed)

16. ☐ Other: _____

17. If a CONTINUING APPLICATION, check appropriate box and supply the requisite information:

☐ Continuation

☐ Divisional

☐ Continuation-in-part (CIP)

of prior application No. _____

18. CORRESPONDENCE ADDRESS

☒ Customer Number or Bar Code Label

06514
(Insert Customer No. or Attach bar code label here)

or ☐ Correspondence address below

NAME				
Address				
City	State	Zip Code		
Country	Telephone	Fax		

CLAIMS	(1) FOR	(2) NUMBER FILED	(3) NUMBER EXTRA	(4) RATE	(5) CALCULATIONS
TOTAL CLAIMS (37 CFR 1.16(c))		28-20 ~	6	X \$ 18.00 ~	\$ 108.00
INDEPENDENT CLAIMS (37 CFR 1.16(b))		4-3 ~	1	X \$ 78.00 ~	\$ 78.00
MULTIPLE DEPENDENT CLAIMS (if applicable) (37 CFR 1.16(d))				\$260.00 ~	\$ 00.00
				BASIC FEE (37 CFR 1.16(e))	\$ 760.00
				Total of above Calculations ~	\$ 946.00
				Reduction by 50% for filing by small entity (Note 37 CFR 1.9, 1.27, 1.28).	
				TOTAL ~	\$ 946.00

19. Small entity status

- a. ☐ A Small entity statement is enclosed
- b. ☐ A small entity statement was filed in the prior nonprovisional application and such status is still proper and desired.
- c. ☐ Is no longer claimed.

20. ☒ A check in the amount of \$ 946.00 to cover the filing fee is enclosed.

21. ☒ A check in the amount of \$ 40.00 to cover the recordal fee is enclosed.

22. The Commissioner is hereby authorized to credit overpayments or charge the following fees to Deposit Account No. 06-1205:

- a. ☒ Fees required under 37 CFR 1.16.
- b. ☒ Fees required under 37 CFR 1.17.
- c. ☐ Fees required under 37 CFR 1.18.

SIGNATURE OF APPLICANT, ATTORNEY, OR AGENT REQUIRED

NAME	T. Thomas C. Gellenthien, Reg. No. 39,693
SIGNATURE	<i>Tom Gellenthien</i>
DATE	September 9, 1999

MULTI-BEAM SCANNING APPARATUS

BACKGROUND OF THE INVENTION

Field of the Invention

5 The present invention relates to a multi-beam scanning apparatus used for a laser beam printer, digital copying machine, and the like.

Related Background Art

10 In recent years, multi-beam scanning apparatuses for simultaneously writing a plurality of lines using a plurality of laser beams are being developed in electrophotographic apparatuses such as a laser beam printer.

15 The multi-beam scanning apparatus simultaneously scans a plurality of laser beams apart from each other. As shown in Fig. 1, in the multi-beam scanning apparatus, a multi-beam semiconductor laser 111 serving as a light source for a multi-beam light source unit 101 emits two laser beams P_1 and P_2 . The laser beams P_1 and P_2 are collimated by a collimator lens 112, 20 irradiate a reflecting surface 103a of a rotary polygon mirror 103 via a cylindrical lens 102, and form an image on a photosensitive member on a rotary drum 105 via an imaging lens 104.

25 The two laser beams P_1 and P_2 are incident on the reflecting surface 103a of the rotary polygon mirror 103, scanned in the main scanning direction, and form

00302525-000000

an electrostatic latent image on the photosensitive member along with main scanning by rotation of the rotary polygon mirror 103 and subscanning by rotation of the rotary drum 105.

5 The cylindrical lens 102 linearly focuses the laser beams P_1 and P_2 on the reflecting surface 103a of the rotary polygon mirror 103. The cylindrical lens 102 has a function of preventing a point image formed on the photosensitive member in the above manner from
10 being distorted due to surface tilt of the rotary polygon mirror 103. The imaging lens 104 is made up of a spherical lens and toric lens. The imaging lens 104 has a function of preventing distortion of a point image on the photosensitive member, similar to the
15 cylindrical lens 102, and a correction function of scanning the point image on the photosensitive member in the main scanning direction at a constant speed.

 The two laser beams P_1 and P_2 are respectively split by a detection mirror 106 at the end of the main
20 scanning plane (X-Y plane), guided to a photosensor 107 on an opposite side to the main scanning plane, and converted into write start signals in a controller (not shown) to be transmitted to the multi-beam
 semiconductor laser 111. The multi-beam semiconductor
25 laser 111 receives the write start signals to start write modulation of the two laser beams P_1 and P_2 .

 By adjusting the write modulation timings of the

two laser beams P_1 and P_2 , the write start (write) position of an electrostatic latent image formed on the photosensitive member on the rotary drum 105 is controlled.

5 The cylindrical lens 102, rotary polygon mirror 103, imaging lens 104, and the like are mounted on the bottom wall of an optical box 108. After the respective optical components are mounted in the optical box 108, the upper opening of the optical box
10 108 is closed with a lid (not shown).

As described above, the multi-beam semiconductor laser 111 simultaneously emits the laser beams P_1 and P_2 . The multi-beam semiconductor laser 111 is integrated via a laser holder 111a with a lens barrel
15 112a incorporating the collimator lens 112, and the integral unit is mounted on a sidewall 108a of the optical box 108 together with a laser driving circuit board 113.

In mounting the multi-beam light source unit 101,
20 the laser holder 111a holding the multi-beam semiconductor laser 111 is inserted into an opening 108b formed in the sidewall 108a of the optical box 108. The laser holder 111a is fitted in the lens barrel 112a of the collimator lens 112, the focal point
25 and optical axis of the collimator lens 112 are adjusted, and the lens barrel 112a is adhered to the laser holder 111a. As shown in Fig. 2A, the laser

00302245-00000

holder 111a is rotated through a predetermined angle θ to adjust a straight line connecting the emission points of the laser beams P_1 and P_2 , i.e., the inclination angle of a laser array N. More

5 specifically, as shown in Fig. 2B, the beam interval between the laser beams P_1 and P_2 emitted by the multi-beam semiconductor laser 111 is adjusted to make a pitch S between imaging points A_1 and A_2 on the rotary drum 105 in the main scanning direction, and a pitch, 10 i.e., line interval T in the subscanning direction coincide with design values. After this adjustment, the laser holder 111a is fixed to the sidewall 108a of the optical box 108 with a screw or the like.

In the prior art, however, when the multi-beam 15 light source unit is to be fixed to the optical box, the whole multi-beam light source unit is rotated through the predetermined angle θ together with the laser driving circuit board, thereby obtaining the line interval T. To realize this, a space enough to rotate 20 the large-area laser driving circuit board must be prepared outside the optical box, which interferes with downsizing of the whole apparatus.

Further, an error allowable value for adjustment of the line interval T is as strict as several μm or 25 less. If the angular adjustment range in assembling the multi-beam light source unit to the optical box is wide, high-precision adjustment is difficult to

rotated to adjust the line interval. Thereafter, screws or the like are tightened to fix the multi-beam light source unit to the housing.

5 A plurality of fixing portions by screws or the like are set. The emission points of laser beams and the center of rotation of the multi-beam light source unit are located on a straight line connecting two of the fixing portions or a planar region defined by straight lines connecting all the fixing portions.

10 Accordingly, the multi-beam light source unit can be very firmly, stably fixed to the housing.

Hence, no rotational shift occurs in the multi-beam light source unit due to shock or the like after the multi-beam light source unit is fixed to the housing.

15

Trouble such as a shift of the rotational angle of the multi-beam light source unit due to free running during screw tightening operation does not occur. Thus, the assembly efficiency and precision can be improved.

20

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a schematic plan view showing a conventional multi-beam scanning apparatus;

25 Figs. 2A and 2B are views for explaining line interval adjustment in the multi-beam scanning apparatus in Fig. 1;

00302621-090099

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENTS

Embodiments of the present invention will be described below with reference to the accompanying drawings.

5 Fig. 3 shows a multi-beam scanning apparatus according to the present invention. In this multi-beam scanning apparatus, a multi-beam semiconductor laser 11 serving as a light source for a multi-beam light source unit 1 emits two laser beams P_1 and P_2 . The laser beams
10 P_1 and P_2 are collimated by a collimator lens 12, irradiate a reflecting surface 3a of a rotary polygon mirror 3 via a cylindrical lens 2, and form an image on a photosensitive member on a rotary drum 5 serving as a
15 surface to be scanned via an imaging lens 4 which constitutes a scanning imaging means together with the rotary polygon mirror 3.

 The two laser beams P_1 and P_2 are incident on the reflecting surface 3a of the rotary polygon mirror 3, scanned in the main scanning direction, and form an
20 electrostatic latent image on the photosensitive member along with main scanning by rotation of the rotary polygon mirror 3 and subscanning by rotation of the rotary drum 5.

 The cylindrical lens 2 linearly focuses the laser
25 beams P_1 and P_2 on the reflecting surface 3a of the rotary polygon mirror 3. The cylindrical lens 2 has a function of preventing a point image formed on the

0032625-00000

photosensitive member in the above manner from being distorted due to surface tilt of the rotary polygon mirror 3. The imaging lens 4 is made up of a spherical lens and toric lens. The imaging lens 4 has a function of preventing distortion of a point image on the photosensitive member, similar to the cylindrical lens 2, and a correction function of scanning the point image on the photosensitive member in the main scanning direction at a constant speed.

The two laser beams P_1 and P_2 are respectively split by a detection mirror 6 at the end of the main scanning plane (X-Y plane), guided to a photosensor 7 on an opposite side to the main scanning plane, and converted into write start signals in a controller (not shown) to be transmitted to the multi-beam semiconductor laser 11. The multi-beam semiconductor laser 11 receives the write start signals to start write modulation of the two laser beams P_1 and P_2 .

By adjusting the write modulation timings of the two laser beams P_1 and P_2 , the write start (write) position of an electrostatic latent image formed on the photosensitive member on the rotary drum 5 is controlled.

The cylindrical lens 2, rotary polygon mirror 3, imaging lens 4, and the like are mounted on the bottom wall of an optical box 8 serving as a housing. After the respective optical components are mounted in the

semiconductor laser 11 in the laser holder 11a, the multi-beam semiconductor laser 11 is rotated through a predetermined rotational angle θ or angle approximate to the angle θ with respect to a reference surface V of the laser holder 11a, as shown in Fig. 5A, thereby adjusting in advance the inclination angle of a straight line, i.e., laser array N connecting the emission points of the laser beams P_1 and P_2 . More specifically, the beam interval between the laser beams P_1 and P_2 emitted by the multi-beam semiconductor laser 11 is adjusted to make a pitch S between imaging points A_1 and A_2 on the rotary drum 5 in the main scanning direction, and a pitch, i.e., line interval T in the subscanning direction coincide with design values in advance (see Fig. 5B). After this adjustment, the multi-beam semiconductor laser 11 is fixed to the laser holder 11a to obtain a unit.

After the lens barrel 12a of the collimator lens 12 is adhered to the laser holder 11a, as described above, the laser holder 11a is temporarily fixed to the sidewall 8a of the optical box 8 with screws 11b fitted in slots of the laser holder 11a, as shown in Fig. 6. While emitting the laser beams P_1 and P_2 , the laser holder 11a is rotated through a small angle $\Delta\theta$ for final adjustment of the line interval T in order to compensate for the precision of each apparatus component and an error at the fit portion of the

multi-beam semiconductor laser 11 itself. In practice,
as indicated by the broken line in Fig. 7, this
adjustment is done after the laser driving circuit
board 13 is mounted on the laser holder 11a. Upon the
5 final adjustment, the screws 11b are tightened to fix
the laser holder 11a to the optical box 8.

The line interval T on the rotary drum must be
adjusted with submicron-order precision. In the first
embodiment, when the multi-beam semiconductor laser is
10 mounted in the laser holder, the laser array N is
roughly adjusted to or near to the predetermined
inclination angle θ . When the laser holder is mounted
in the optical box together with the laser driving
circuit board, the angle is finally slightly adjusted
15 to correct an assembly error and the like. Therefore,
the final line interval adjustment precision is very
high, and the adjustment time can be greatly shortened
compared to the conventional wide-range angular
adjustment on the optical box. In addition, the
20 large-area laser driving circuit board need not be
rotated outside the optical box, and the apparatus can
be downsized.

As a result, this embodiment can realize a
small-size, high-precision multi-beam scanning
25 apparatus with low assembly cost.

Note that this embodiment uses the laser chip with
two emission points. However, the number of emission

00302625-000999

5

10

20

25

semiconductor laser 41 can advantageously reduce optical aberration because all the emission points can be made close to the optical axis of the collimator lens. A positioning hole 41b is formed in a disk-like laser holder 41a as a positioning reference used to adjust the rotational angle θ for adjusting beam intervals T_1 to T_3 .

The surface emission type laser can increase the degree of freedom for the positions of the emission points to facilitate distribution of the mounting tolerance.

As described above, in the multi-beam scanning apparatus of the present invention, the two laser beams P_1 and P_2 emitted by the multi-beam semiconductor laser 11 are scanned by the rotary polygon mirror inside the optical box 8, and form an image on the photosensitive member on the rotary drum via the imaging lens. To adjust the line interval T and the like on the photosensitive member, when the multi-beam semiconductor laser 11 is to be mounted in the laser holder 11a, the multi-beam semiconductor laser 11 is rotated to incline the laser array N at the predetermined inclination angle θ . Then, the multi-beam semiconductor laser 11 is fixed to the laser holder 11a. In mounting the multi-beam light source unit 1 in the optical box 8, the whole multi-beam light source unit 1 is only slightly inclined to compensate

for the component precision and the like.

With this arrangement, the present invention exhibits the following effects.

5 The beam interval between a plurality of laser beams emitted by the multi-beam semiconductor laser can be adjusted within a short time with high precision. Accordingly, the apparatus can attain high resolution, the assembly cost can be greatly reduced, and the whole apparatus can be downsized.

10 The fourth embodiment of the present invention will be described below. Figs. 11A and 11B are schematic views showing the fourth embodiment of the multi-beam light source unit. The whole arrangement of the multi-beam scanning apparatus is the same as that
15 shown in Fig. 3, and a description thereof will be omitted. The multi-beam light source unit will be explained.

As shown in Figs. 11A and 11B, after a lens barrel
20 12a of a collimator lens 12 is adhered to a laser holder 11a, the laser holder 11a is temporarily fixed to a sidewall 8a of an optical box 8 with screws 14 (see Figs. 11A and 11B) serving as fixing means fitted in holes in the laser holder 11a. While emitting laser
25 beams P_1 and P_2 , the laser holder 11a is rotated to adjust the inclination angle θ in order to adjust the line interval T, as shown in Fig. 5A.

This adjustment is to adjust the beam interval

5

box 8.

10

15

25

The center O of rotation is also positioned on the straight lines L_1 to L_3 connecting the fixing portions 14a to 14c or within the planar region N defined by the straight lines L_1 to L_3 .

With this layout, the emission points of the two laser beams P_1 and P_2 always fall within the range defined by lengths obtained by converting the intervals between the fixing portions 14a to 14c into main scanning and subscanning components. The wide range including the center O of rotation can be firmly fixed to effectively prevent vertical and horizontal tilt of the multi-beam light source unit 1.

Particularly when the screws 14 are used as fixing means, the laser holder 11a and the sidewall 8a of the optical box 8 are pressed against each other via a fastening surface M. A clearance K is set as an adjustment margin for angular adjustment rotation. The laser holder 11a is moved within this range.

The fastening surface M at the fixing portions 14a to 14c of the screws 14 provides the highest fastening reliability and high stability because the laser holder 11a and sidewall 8a contact each other at fastening pressure generation positions. Note that if the fastening surface M does not completely coincide with the positions of the screws 14, the same effects can be obtained so long as they are close to each other. The position and shape of the fastening surface M and the

number of fastening surfaces M need not be limited.

The fourth embodiment adopts the screws as fixing means, but may adopt an adhesion means with an ultraviolet-curing adhesive or the like. The number of emission points is not limited and may be arbitrarily set to two or more.

The collimator lens is adhered to the lens barrel preferably with the ultraviolet-curing adhesive, but may be adhered with another adhesive.

10 According to the fourth embodiment, the multi-beam
light source unit is fastened to the sidewall of the
optical box with screws at three or more fixing
portions. The center of rotation of the multi-beam
light source unit and the emission points of respective
15 laser beams locate on straight lines connecting the
fixing portions or within the planar region defined by
straight lines connecting all the fixing portions.
Thus, the multi-beam light source unit can be stably,
firmly mounted in the optical box.

20 The fourth embodiment can realize a low-cost,
high-performance multi-beam scanning apparatus capable
of effectively avoiding troubles such as a rotational
shift of the multi-beam light source unit upon
high-precision line interval adjustment, and free
25 running during fastening upon adjustment.

Fig. 12 shows the fifth embodiment of the multi-beam light source unit. When the position of the

emission point of a multi-beam semiconductor laser 11 greatly offsets from the center O of rotation of a laser holder 11a due to low component precision, the multi-beam semiconductor laser 11 is adjusted again in the laser holder 11a. To realize this, an adjustment member 15 for adjusting the relative position is used and fastened to the laser holder 11a with screws 16.

The adjustment member 15 is relatively moved together with the multi-beam semiconductor laser 11 with respect to the laser holder 11a to adjust a laser array connecting laser beams P_1 and P_2 so as to pass through the center O of rotation. Then, the adjustment member 15 is fastened to the laser holder 11a with the screws 16.

Even if the positional precision of emission points varies in the component, the adjustment member 15 can adjust the positions of the emission points to locate them on straight lines L_1 to L_3 connecting fixing portions 14a to 14c or within the planar region N defined by all the straight lines L_1 to L_3 , as shown in Fig. 11A.

The package shape of the multi-beam semiconductor laser can advantageously be selected from a wide range.

The edge emission type multi-beam semiconductor laser 11 on which a plurality of emission points are aligned may be replaced with a multi-beam semiconductor laser 41 having a surface emission type laser chip 42

on which a plurality of emission points 42a to 42d are two-dimensionally arrayed, as shown in Fig. 10. This multi-beam semiconductor laser 41 can advantageously reduce optical aberration because all the emission points can be made close to the optical axis of the collimator lens. A positioning hole 41b is formed in a disk-like laser holder 41a as a positioning reference used to adjust the inclination angle θ for adjusting line intervals T_1 to T_3 .

The surface emission type laser can increase the degree of freedom for the positions of the emission points to facilitate distribution of the mounting tolerance.

As described above, in the multi-beam scanning apparatus of the present invention, the two laser beams P_1 and P_2 emitted by the multi-beam semiconductor laser are scanned by the rotary polygon mirror inside the optical box 8, and form an image on the photosensitive member on the rotary drum via the imaging lens. To adjust the line interval and the like on the photosensitive member, the laser holder 11a is fixed to the sidewall 8a of the optical box 8 after rotation through a predetermined angle. The fixing portions 14a to 14c are set to locate the emission points of the laser beams P_1 and P_2 and the center O of rotation on straight lines connecting the fixing portions 14a to 14c by the screws 14 or within the planar region N

defined by these lines. The laser holder 11a is firmly, stably mounted with high positional precision.

With this arrangement, the present invention exhibits the following effects.

5 The line interval between a plurality of laser
beams emitted by the multi-beam semiconductor laser can
be adjusted with high precision, and the laser holder
can be firmly, stably mounted.

The present invention can realize a low-cost,
10 high-performance multi-beam scanning apparatus free
from any multi-beam line interval error.

WHAT IS CLAIMED IS:

1. A multi-beam scanning apparatus comprising:
a multi-beam semiconductor laser;
a laser holder holding said multi-beam
5 semiconductor laser;
a multi-beam light source unit having said
multi-beam semiconductor laser and said laser holder;
scanning imaging means for scanning a plurality of
laser beams emitted by said multi-beam semiconductor
10 laser to form an image on a surface to be scanned; and
a housing supporting said scanning imaging means
and said multi-beam light source unit,
wherein said multi-beam semiconductor laser is
fixed to said laser holder with inclination at or near
15 a predetermined rotational angle for adjusting a beam
interval between the plurality of laser beams.
2. An apparatus according to claim 1, wherein
said multi-beam semiconductor laser has a laser array
20 fixed with inclination with respect to a reference
surface of said laser holder.
3. An apparatus according to claim 1, wherein
said multi-beam semiconductor laser has a plurality of
25 aligned emission points.
4. An apparatus according to claim 1, wherein

00302625-000000

said multi-beam semiconductor laser has a plurality of two-dimensionally arrayed emission points.

5. An apparatus according to claim 1, wherein
5 said laser holder is integrated with a lens barrel
holding a collimator lens.

6. A multi-beam light source unit comprising:
a multi-beam semiconductor laser for emitting a
10 plurality of laser beams;
a laser holder holding said multi-beam
semiconductor laser; and
a multi-beam light source unit having said
multi-beam semiconductor laser and said laser holder,
15 wherein said multi-beam semiconductor laser is
fixed to said laser holder with inclination at or near
a predetermined rotational angle for adjusting a beam
interval between the plurality of laser beams.

20 7. A unit according to claim 6, wherein said
multi-beam semiconductor laser has a laser array fixed
with inclination with respect to a reference surface of
said laser holder.

25 8. A unit according to claim 6, wherein said
multi-beam semiconductor laser has a plurality of
aligned emission points.

straight lines connecting all the plurality of fixing portions.

12. An apparatus according to claim 11, wherein
5 said fixing means has at least three fixing portions.

13. An apparatus according to claim 11, wherein
said fixing means has a fixing portion fastened by a
screw.
10

14. An apparatus according to claim 11, wherein
said fixing means has a fixing portion adhered with an
adhesive.

15 15. An apparatus according to claim 11, wherein
said multi-beam semiconductor laser has a plurality of
aligned emission points.

16. An apparatus according to claim 11, wherein
20 said multi-beam semiconductor laser has a plurality of
two-dimensionally arrayed emission points.

17. An apparatus according to claim 11, wherein
said laser holder comprises an adjustment member for
25 adjusting a relative position of said multi-beam
semiconductor laser.

21. A unit according to claim 19, wherein said fixing means has a fixing portion fastened by a screw.

22. A unit according to claim 19, wherein said
5 fixing means has a fixing portion adhered with an adhesive.

23. A unit according to claim 19, wherein said
10 multi-beam semiconductor laser has a plurality of aligned emission points.

24. A unit according to claim 19, wherein said
15 multi-beam semiconductor laser has a plurality of two-dimensionally arrayed emission points.

25. A unit according to claim 19, wherein said
20 laser holder comprises an adjustment member for adjusting a relative position of said multi-beam semiconductor laser.

26. A unit according to claim 19, wherein said laser holder is integrated with a lens barrel holding a collimator lens.

003222-00000

060908

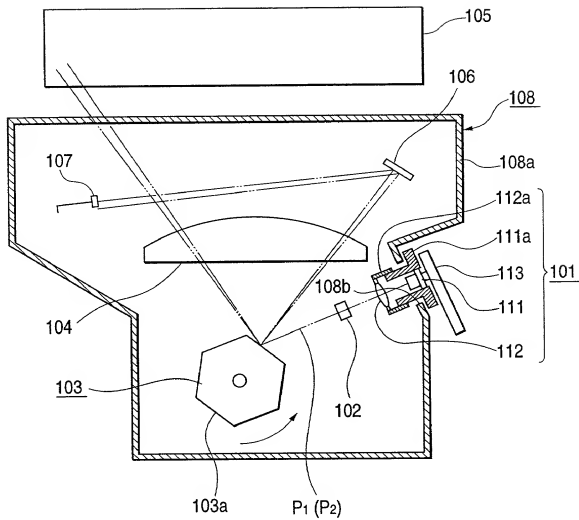


FIG. 2A

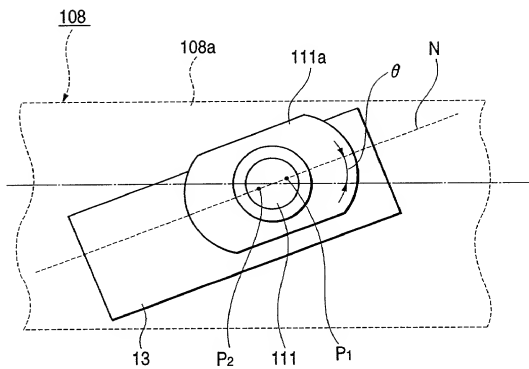


FIG. 2B

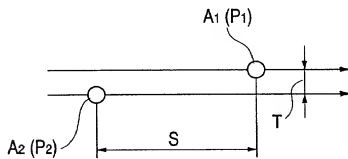


FIG. 3

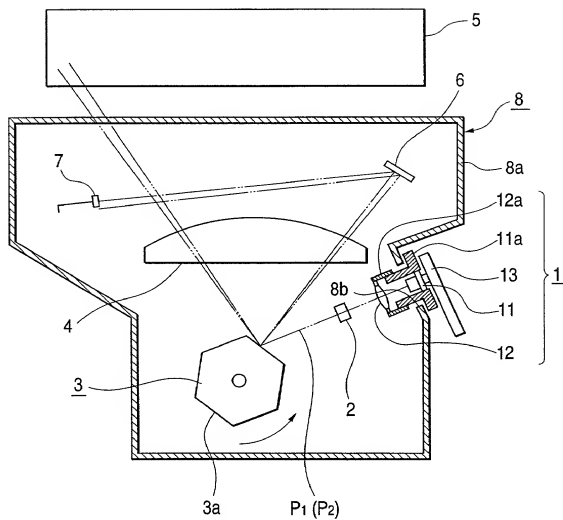


FIG. 5A

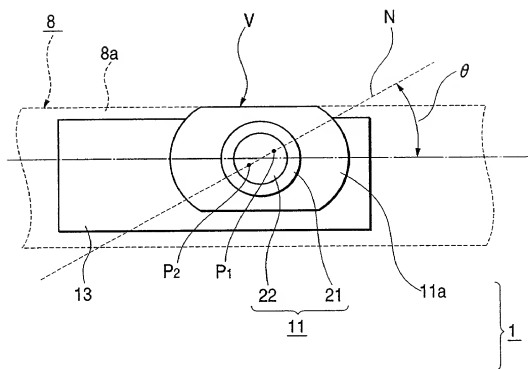


FIG. 5B

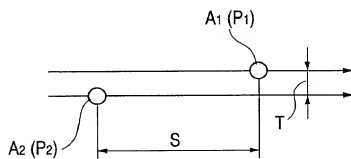


FIG. 6

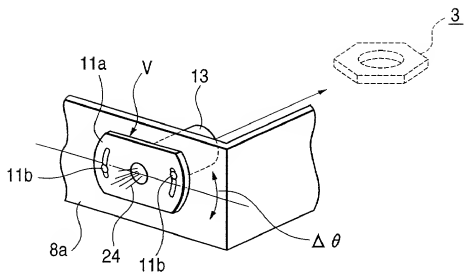


FIG. 7

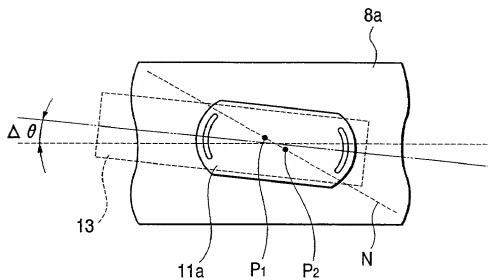


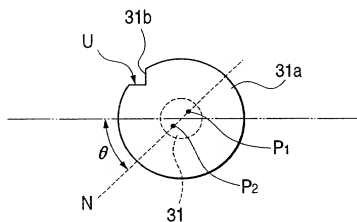
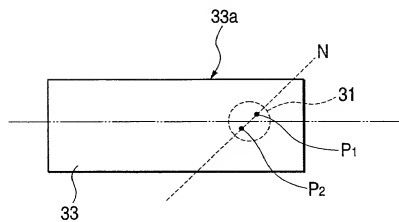
FIG. 8*FIG. 9*

FIG. 10

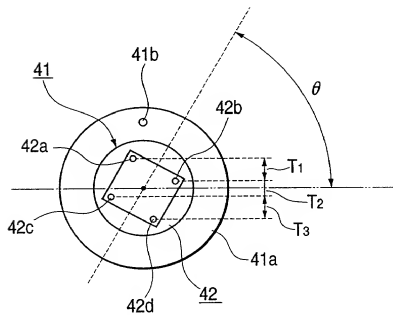


FIG. 12

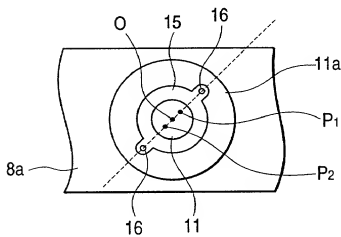
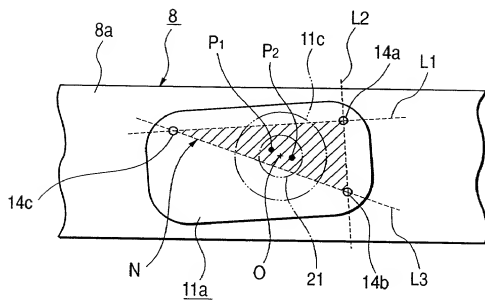
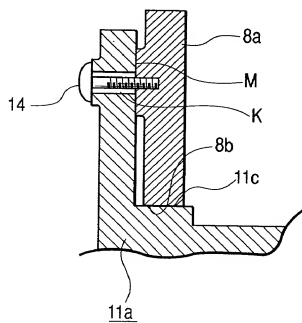


FIG. 11A**FIG. 11B**

COMBINED DECLARATION AND POWER OF ATTORNEY
FOR PATENT APPLICATION

(Page 1)

As a below named inventor, I hereby declare that:

My residence, post office address and citizenship are as stated below next to my name;

I believe I am the original, first and sole inventor (if only one name is listed below) or an original, first and joint inventor (if plural names are listed below) of the subject matter which is claimed and for which a patent is sought on the invention entitled _____

MULTI-BEAM SCANNING APPARATUS

the specification of which ☒ is attached hereto ☐ was filed on _____ as United States Application No. or PCT International Application No. _____ and was amended on _____ (if applicable).

I hereby state that I have reviewed and understand the contents of the above-identified specification, including the claims, as amended by any amendment referred to above.

I acknowledge the duty to disclose information which is material to patentability as defined in 37 CFR §1.56.

I hereby claim foreign priority benefits under 35 U.S.C. §119(a)-(d) or §365(b), of any foreign application(s) for patent or inventor's certificate, or §365(a) of any PCT international application which designates at least one country other than the United States, listed below and have also identified below any foreign application for patent or inventor's certificate, or PCT international application having a filing date before that of the application on which priority is claimed:

Country	Application No.	Filed (Day/Mo./Yr.)	(Yes/No) Priority Claimed
JAPAN	10-279352	14 September 1998	Yes
JAPAN	10-355353	30 November 1998	Yes

I hereby appoint the practitioners associated with the firm and Customer Number provided below to prosecute this application and to transact all business in the Patent and Trademark Office connected therewith, and direct that all correspondence be addressed to the address associated with that Customer Number:

FITZPATRICK, CELLA, HARPER & SCINTO

Customer Number: 05514

I hereby declare that all statements made herein of my own knowledge are true and that all statements made on information and belief are believed to be true; and further that these statements were made with the knowledge that willful false statements and the like so made are punishable by fine or imprisonment, or both, under Section 1001 of Title 18 of the United States Code and that such willful false statements may jeopardize the validity of the application or any patent issued thereon.

Full Name of Sole or First Inventor SHIN MOGI

Inventor's signature Shin Mogi

Date August 31, 1999 Citizen/Subject of JAPAN

Residence 11-1-304, Chiyoda 1-chome, Kashiwa-shi, Chiba-ken,
Japan

Post Office Address c/o Canon Kabushiki Kaisha
30-2, Shimomaruko 3-chome, Ohta-ku, Tokyo, Japan

Full Name of Second Joint Inventor, if any YASUTAKA NARUGE

Second Inventor's signature Yasutaka Naruge

Date August 31, 1999 Citizen/Subject of JAPAN

Residence 11-33, Shinmachi 4-chome, Toride-shi, Ibaraki-ken,
Japan

Post Office Address c/o Canon Kabushiki Kaisha
30-2, Shimomaruko 3-chome, Ohta-ku, Tokyo, Japan

00302525-000999